

Solving Large-scale problems using JuMP

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JuMP Developers meet-up

Santiago, March 13, 2019

Agenda

- LAMPS
- Research Projects
- Benchmarks
- SDDP
- Since then



More than 20 students most Ph.D. and M.Sc.
candidates and researchers

6 professors from PUC-Rio from different backgrounds
mainly in Optimization, Statistics and Temporal series

Mostly problems in energy, finance and oil and gas
production

Why we use JuMP?



- JuMP was the major reason to migrate and convert every project in our laboratory(LAMPS) to Julia
- Versatile and easy to use (even for undergrad)
- Why get stuck with many different languages and solvers

Research Projects



- Churn and Fraud Detection in real time
- Incorporating the effect of climate variability and contingencies in the optimal contracting strategy of transmission-usage amounts
- Stochastic Dual Dynamic Programming Dispatch Tool
- Optimization model with uncertainty in real time for offshore platforms

Migrating to Julia/JuMP



As I finished my Ph.D. my advisor insists to port everything to Julia(the hole SDDP)

Cuts	Julia(sec.)	C++(sec.)
1	6.8	1.7
5	7.6	4.3
10	10.6	37.1
15	55.3	54.0
20	69.8	68.0
25	84.8	81.8
30	98.9	97.3

Humanitarian

Different languages

Inst.	Gap(%)			Time(sec.)		
	Julia	C++	Mosel	Julia	C++	Mosel
v10e20_s1	0.9	0.9	0.37	22	77	64
v10e20_s2	0.68	0.68	0.76	41	126	100
v10e20_s2	0.07	0.07	0.69	25	92	78
v10e20_s4	0.84	0.84	0.41	71	146	133
v10e20_s5	0.41	0.41	0.57	118	154	171
v12e25D	0.5	0.49	0.72	23	38	33
v13e30_s1	0.58	0.58	N/A	11	28	N/A
v13e30_s2	0.8	0.8	0.51	192	376	239
v13e30_s3	0.0	0.0	0.37	14	31	44
v13e30_s4	0.0	0.0	0.6	51	97	60
v13e30_s5	0.0	0.0	0.46	92	150	135

Humanitarian

Different solvers in Julia/JuMP

Inst.	Gap(%)			Time(sec.)		
	Cplex	Gurobi	Xpress	Cplex	Gurobi	Xpress
v10e20_s1	0.9	0.53	0.37	22	124	60
v10e20_s2	0.68	0.77	0.0	41	163	117
v10e20_s2	0.07	0.67	0.69	25	79	70
v10e20_s4	0.84	0.15	0.41	71	127	126
v10e20_s5	0.41	0.0	0.57	118	222	151
v12e25D	0.5	0.24	0.41	23	49	31
v13e30_s1	0.58	0.89	0.33	11	39	20
v13e30_s2	0.8	0.62	0.47	192	245	240
v13e30_s3	0.0	0.15	0.01	14	51	43
v13e30_s4	0.0	0.18	0.84	51	74	51
v13e30_s5	0.0	0.47	0.78	92	118	109

Hydrothermal Dispatch

Inst.	Matlab			Julia		
	CP	BB	BC	CP	BB	BC
3 Bus, k = 0	0.1	0.5	0.4	0.0	0.0	0.0
3 Bus, k = 1	0.1	0.4	0.4	0.0	0.0	0.1
24 Bus reduced, k = 0	0.0	0.8	0.2	0.0	0.1	0.0
24 Bus reduced, k = 1	35.0	4.1	67.2	12.3	2.0	81.2
24 Bus, k = 0	0.0	2.0	1.6	0.0	0.1	0.3
24 Bus, k = 1	223.2	62.0	1030. 2	11.6	39.0	121.8

C++/Cplex(Concert)

points\dim	10	30	100	500	5000
10	0.4	0.5	0.7	1.8	15.3
15	1.0	1.2	1.7	5.5	53.1
20	1.8	2.4	3.8	12.7	
30	5.0	7.2	12.4	47.6	

Julia/JuMP(Cplex)

points\dim	10	30	100	500	5000
10	0.3	0.3	0.5	1.8	19.4
15	0.5	0.8	1.5	6.1	69.6
20	1.1	1.7	3.5	14.9	
30	3.7	6.2	12.9	60.0	

How to solve multistage stochastic problems?

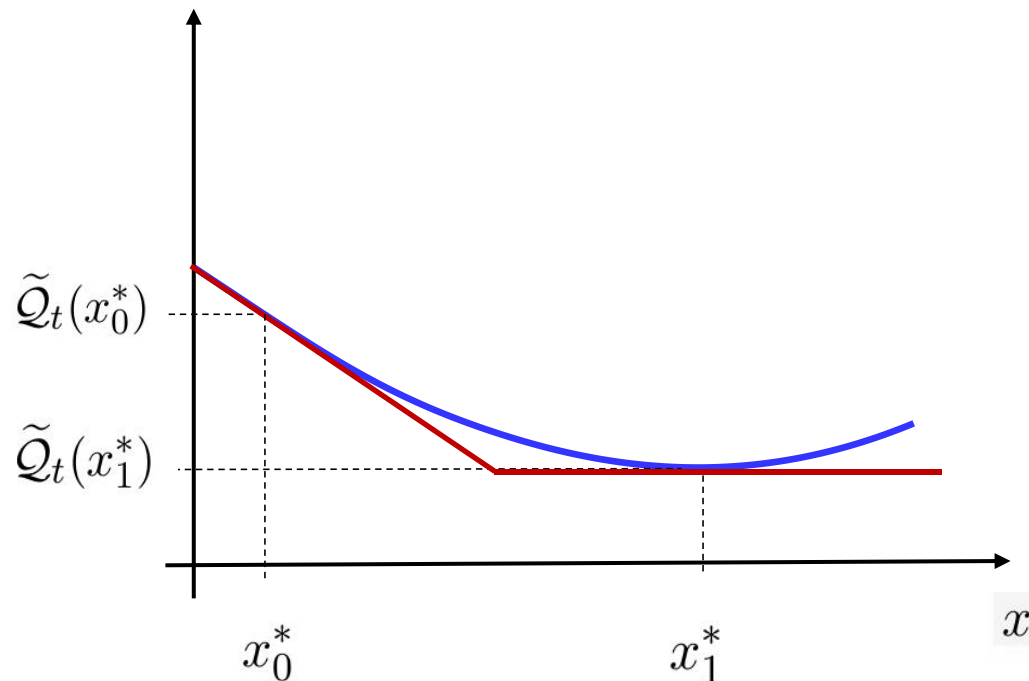
$$\max_{\substack{\mathbf{A}_1 \mathbf{x}_1 = \mathbf{b}_1 \\ \mathbf{x}_1 \geq 0}} \mathbf{c}_1^\top \mathbf{x}_1 + \mathbb{E} \left[\max_{\substack{\mathbf{A}_2 \mathbf{x}_2 = \mathbf{b}_2 - \mathbf{B}_2 \mathbf{x}_1 \\ \mathbf{x}_2 \geq 0}} \mathbf{c}_2^\top \mathbf{x}_2 + \dots + \mathbb{E} \left[\max_{\substack{\mathbf{A}_T \mathbf{x}_T = \mathbf{b}_T - \mathbf{B}_T \mathbf{x}_{T-1} \\ \mathbf{x}_T \geq 0}} \mathbf{c}_T^\top \mathbf{x}_T \mid \xi_{T-1} \right] \dots \mid \xi_1 \right]$$

Bellman equations and cost function

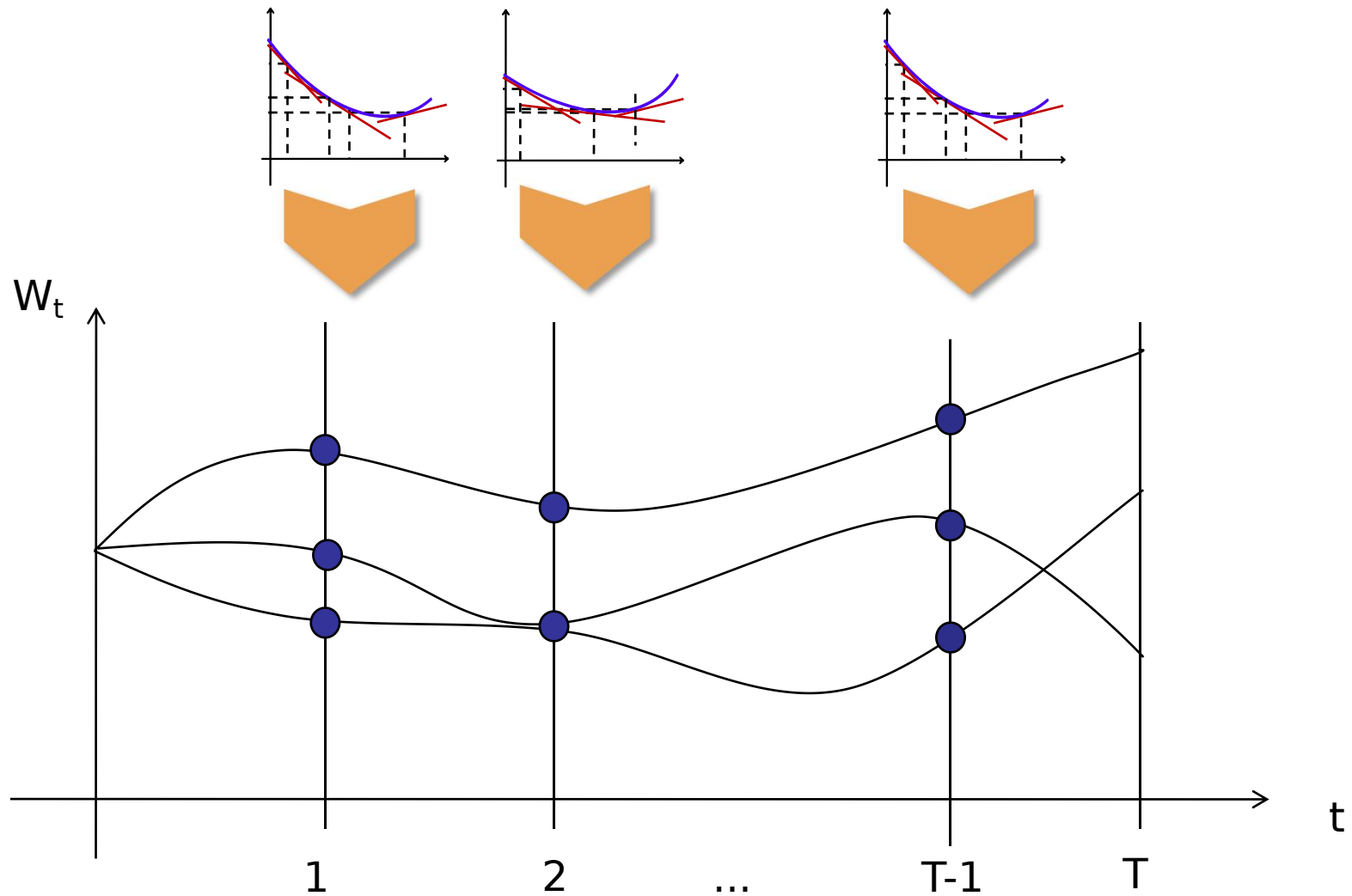
$$\begin{aligned} Q_t(\mathbf{x}_{t-1}, \xi_{ts}) &= \max_{\mathbf{x}_t} \mathbf{c}_{ts}^\top \mathbf{x}_t + Q_{t+1}(\mathbf{x}_t) \\ &\text{s.t. } \mathbf{A}_{ts} \mathbf{x}_t = \mathbf{b}_{ts} - \mathbf{B}_{ts} \mathbf{x}_{t-1} \\ &\quad \mathbf{x}_t \geq 0 \end{aligned}$$

Approximate the future cost function using a piecewise linear function

$$\Omega_t(\mathbf{x}_{t-1}) = \max_{l \in \mathcal{I}_t} \{ \tilde{Q}_t(\mathbf{x}_{t-1,l}) + \tilde{\mathbf{g}}_{tl}^\top (\mathbf{x}_{t-1} - \mathbf{x}_{t-1,l}) \}, \quad \forall t \in \mathcal{H}$$



SDDP



SDDP Issues

- The first issue was memory consumption our model were consuming more than 128Gb of memory(Computational bottleneck)
- Couldn't remove constraints making difficult to remove cuts to optimize memory consumption
- Performance decrease compared to Low-level API

How can I solve those problems?

- I liked JuMP very much but for SDDP there were some problems
- I still manage to maintain the **construction** of the problem **using JuMP** but to change RHS and add constraints I had to use Cplex low-level API
- Choosing solver. I did benchmark tests to choose the best solver: Cplex was the best with Gurobi soon after

Solution

The difference of using low-level API (1355 cuts)

CPLEX API	
1360 MB	350 min
JuMP	
1514 MB	826 min

Adding constraints(Backward) was 2.2 times slower

Upper bound evaluation(chgrhs) was 3.41 times slower

JuMP has a limit?

Memory consumption and time of @constraint #969

 Closed

Thuener opened this issue on Feb 20, 2017 · 24 comments



Thuener commented on Feb 20, 2017 • edited ▾

+ 😊 ...

I'm having some issues with memory consumption on JuMP. I have a problem that has too many constraints and the JuMP structures for macro **@constraint** is consuming too much memory.

Benchmark JuMP/Julia



Vectorized

```
@constraint(m, θ .<= coef*x )
```

Scalar 1

```
for i in 1:size(coef,1)
    @constraint(m, θ <= sum(coef[i,j]*x[j] for j = 1:size(coef,2)))
end
```

Scalar 2

```
@constraint(m, [i = 1:size(coef,1)],
    θ <= sum(coef[i,j]*x[j] for j = 1:size(coef,2)))
```

Cplex API

```
rhs = zeros(C)
coef = hcat(-coef, ones(C));
CPLEX.add_constrs!(m.internalModel.inner, coef, '<', rhs)
```

```
m = Model(solver=CplexSolver())
@variable(m, θ <= x[1:N] <= 1)
@variable(m, θ <= θ <= 1000)

@objective(m, Max, θ )
```

Performance evolution



Adding constraints time(sec.) for each Julia, JuMP and Cplex versions

Vec.	Scalar 1	Scalar 2	Cplex API
Julia 0.6.3 JuMP 0.18.1 Cplex 0.3.2			
12.5	5.0	5.1	2.0
12.5	4.9	5.0	1.8
Julia 0.7.0 JuMP 0.18.5 Cplex 0.4.3			
11.1	4.9	4.9	2.7
11.1	4.8	4.8	2.7
Julia 1.0.3 JuMP 0.18.5 Cplex 0.4.3			
11.1	4.9	5.2	2.6
10.9	5.1	5.0	2.7
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
22.4	13.1	13.7	2.7
21.1	13.2	13.8	2.7

C =
300,000
N =
100

This model is
solved in 5
seconds

Memory evolution

Adding constraints MB
for each Julia, JuMP and
Cplex versions



Vec.	Scalar 1	Scalar 2	Cplex API
Julia 0.6.3 JuMP 0.18.1 Cplex 0.3.2			
1069	1125	1148	348
992	1118	1123	347
Julia 0.7.0 JuMP v0.18.5 Cplex 0.4.3			
1074	1111	1135	364
966	1130	1203	347
Julia 1.0.3 JuMP 0.18.5 Cplex 0.4.3			
1030	1198	1178	348
967	1234	1136	347
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
1115	924	1011	303
1047	986	1004	347

Direct Model

Time

Memory

Vec.	Scalar 1	Scalar 2	Cplex API
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
20.7	12.1	12.7	2.5
20.0	12.2	12.7	2.6

Vec.	Scalar 1	Scalar 2	Cplex API
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
1206	965	963	304
1130	1022	885	384

Direct Model

Direct Model

Time

Memory

Vec.	Scalar 1	Scalar 2	Cplex API
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
20.7	12.1	12.7	2.5
20.0	12.2	12.7	2.6

Vec.	Scalar 1	Scalar 2	Cplex API
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
1206	965	963	304
1130	1022	885	384

Direct Model

Vec.	Scalar 1	Scalar 2	Cplex API
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
12.0	6.0	6.5	2.5
12.2	6.0	6.3	2.5

Vec.	Scalar 1	Scalar 2	Cplex API
Julia 1.0.3 JuMP 0.19.0 Cplex v0.4.3			
565	495	498	304
545	495	498	384

Since then

- Julia and JuMP change the way we develop software
- Now all our projects and courses are develop in Julia
- We are constructing frameworks in Julia using JuMP
- Our development and research is much faster making possible to construct big research with a small team
- LAMPS have more than **15** publications using JuMP and at least **14** in development

Thanks JuMP!

