



Stochastic Programming for Hydropower Operations

Modeling and Algorithms

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Motivation

- Simulation of hydro power operations → Decision-support

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 - Price forecasts
 - Irregular power production: solar and wind
 - Nuclear power phase-out

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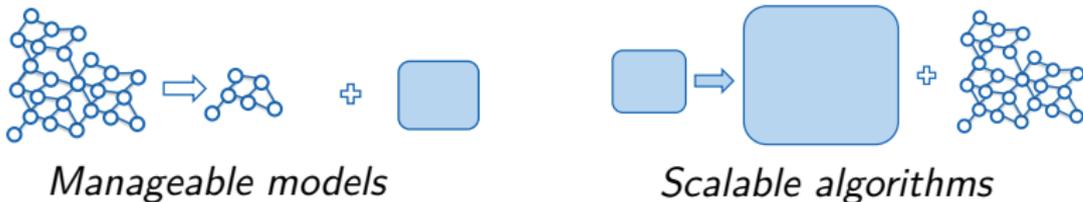
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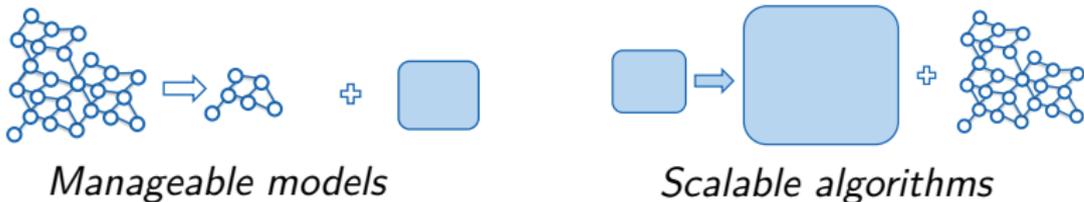
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Stochastic programming for hydro power operations

- Optimal orders on the day-ahead market
- Maintenance scheduling
- Long-term investments
- Wind/solar uncertainties

Stochastic programming for hydro power operations

- Optimal orders on the day-ahead market
- Maintenance scheduling
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Advantages

- Multiple scenarios → More accurate models
- Parallel decomposition → Faster computations

Contribution

Julia modules

- StochasticPrograms.jl
- LShapedSolvers.jl
- HydroModels.jl

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- StochasticPrograms.jl
- LShapedSolvers.jl
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Software Innovations

- Deferred model creation
- Data injection

Content

- Initial approach

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- StochasticProgramming.jl

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- Initial approach
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- LShapedSolvers.jl
- HydroModels.jl
- Final remarks

Initial Approach

- HydroModel
 - Data
 - JuMP model

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 - JuMP model
- Julia struct for each model: ShortTerm, DayAhead

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- Parallel decomposition: L-shaped on StructJuMP.jl models

Initial Approach

- HydroModel
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 - JuMP model
- Julia struct for each model: ShortTerm, DayAhead
- Parallel decomposition: L-shaped on StructJuMP.jl models
- Performance: Solve extended form using MathProgBase solvers

Initial Approach

```

function define_structjump_problem(model::DayAheadModel)
    model.internalmodels[:structured] = StructuredModel(num_scenarios = numscenarios(model))
    params = model.modeldata
    ..
    @variable(internalmodel,xt_i[t = model.hours] >= 0)
    ..
    for s in 1:numscenarios(model)
        block = StructuredModel(parent = internalmodel, id = s)
        ...
        @variable(block,Q[p = model.plants, q = model.segments, t = model.hours],
            lowerbound = 0,upperbound = params.Q[(p,q)])
        @variable(block,S[p = model.plants, t = model.hours] >= 0)
        ...
        @expression(block,value_of_stored_water,
            params.λ_f*sum(M[p,hours(model.horizon)]*sum(params.μ[i,1]
                for i = params.Qd[p])
                for p = model.plants))
        # Define objective
        @objective(block, Max, net_profit + value_of_stored_water)
        ...
        @constraint(block,production[s = model.scenarios, t = model.hours],
            H[s,t] == sum(params.μ[p,q]*Q[s,p,q,t]
                for p = model.plants, q = model.segments)
            )
        ...
    end
end

```

Initial Approach

```

function define_dep_problem(model::DayAheadModel)
    model.internalmodels[:dep] = Model()
    params = model.modeldata
    ...
    @variable(internalmodel,xt_i[t = model.hours] >= 0)
    ...
    @variable(block,Q[s = model.scenarios, p = model.plants, t = model.hours],
        lowerbound = 0, upperbound = params.Q[(p,q)])
    @variable(block,S[s = model.scenarios, p = model.plants, t = model.hours] >= 0)
    ...
    @expression(block,value_of_stored_water,
        sum(scenarios[s].π*params.λ_f*sum(M[s,p]*sum(params.μ[i,l]
            for i = params.Qd[p]
            for p = model.plants)
            for s = model.scenarios))
    # Define objective
    @objective(block, Max, net_profit + value_of_stored_water)
    ...
    @constraint(block,production[s = model.scenarios, t = model.hours],
        H[s,t] == sum(params.μ[p,q]*Q[s,p,q,t]
            for p = model.plants, q = model.segments)
    )
    ...
end

```

Initial Approach - Issues

- A lot of code repetition

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- A lot of code repetition
- No clearcut way to calculate stochastic measures: EVPI, VSS
- The model creation is somewhat inflexible
- Parallel L-shaped using the Distributed module in Julia...
- ...but StructJuMP relies on MPI
- Creating a new hydromodel involves reimplementing a new type

New Approach

- StochasticPrograms.jl
 - Flexible model creation

- HydroModels.jl

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 - Model creation focused on data and optimization formulation
 - Efficient model reinitialization

New Approach

- StochasticPrograms.jl
 - Flexible model creation
 - Parallel capabilities based on the Distributed module
 - Stochastic programming constructs
- HydroModels.jl
 - Model creation focused on data and optimization formulation
 - Efficient model reinitialization
 - Predefined models
 - Short-term production planning
 - Optimal orders on the day-ahead market

StochasticPrograms.jl - Simple Example

$$\begin{aligned} \underset{x_1, x_2 \in \mathbb{R}}{\text{minimize}} \quad & 100x_1 + 150x_2 + \mathbb{E}_\omega[Q(x_1, x_2, \xi)] \\ \text{s.t.} \quad & x_1 + x_2 \leq 120 \\ & x_1 \geq 40 \\ & x_2 \geq 20 \end{aligned}$$

where

$$\begin{aligned} Q(x_1, x_2, \xi) = \min_{y_1, y_2 \in \mathbb{R}} \quad & q_1(\xi)y_1 + q_2(\xi)y_2 \\ \text{s.t.} \quad & 6y_1 + 10y_2 \leq 60x_1 \\ & 8y_1 + 5y_2 \leq 80x_2 \\ & 0 \leq y_1 \leq d_1(\xi) \\ & 0 \leq y_2 \leq d_2(\xi) \end{aligned}$$

StochasticPrograms.jl - Simple Example

```
sp = StochasticProgram(solver=ClpSolver())

@first_stage sp = begin
    @variable(model, x1 >= 40)
    @variable(model, x2 >= 20)
    @objective(model, Min, 100*x1 + 150*x2)
    @constraint(model, x1+x2 <= 120)
end

@second_stage sp = begin
    @decision x1 x2
    s = scenario
    @variable(model, 0 <= y1 <= s.d[1])
    @variable(model, 0 <= y2 <= s.d[2])
    @objective(model, Min, s.q[1]*y1 + s.q[2]*y2)
    @constraint(model, 6*y1 + 10*y2 <= 60*x1)
    @constraint(model, 8*y1 + 5*y2 <= 80*x2)
end
```

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    @constraint(model, 8*y1 + 5*y2 <= 80*x2)
end
```

Creates a generator function for the first stage model

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```

```
end
```

```
@second_stage sp = begin
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    @variable(model, 0 <= y1 <= s.d[1])
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    @constraint(model, 6*y1 + 10*y2 <= 60*x1)
    @constraint(model, 8*y1 + 5*y2 <= 80*x2)
```

```
end
```

Creates a generator function for the second stage model

StochasticPrograms.jl - Simple Example

```
sp = StochasticProgram(solver=ClpSolver())
```

```
@first_stage sp = begin
    @variable(model, x1 >= 40)
    @variable(model, x2 >= 20)
    @objective(model, Min, 100*x1 + 150*x2)
    @constraint(model, x1+x2 <= 120)
```

```
end
```

```
@second_stage sp = begin
    @decision x1 x2
    s = scenario
    @variable(model, 0 <= y1 <= s.d[1])
    @variable(model, 0 <= y2 <= s.d[2])
    @objective(model, Min, s.q[1]*y1 + s.q[2]*y2)
    @constraint(model, 6*y1 + 10*y2 <= 60*x1)
    @constraint(model, 8*y1 + 5*y2 <= 80*x2)
```

```
end
```

Explicitly denote that some variables originate from the first stage

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end

@second_stage sp = begin
    @decision x1 x2
    s = scenario
    @variable(model, 0 <= y1 <= s.d[1])
    @variable(model, 0 <= y2 <= s.d[2])
    @objective(model, Min, s.q[1]*y1 + s.q[2]*y2)
    @constraint(model, 6*y1 + 10*y2 <= 60*x1)
    @constraint(model, 8*y1 + 5*y2 <= 80*x2)
end
```

Injection point for scenario data

StochasticPrograms.jl - Simple Example

```
struct SimpleScenario <: AbstractScenarioData
    p::Float64
    d::Vector{Float64}
    q::Vector{Float64}
end
```

```
StochasticPrograms.probability(s::SimpleScenario) = s.p
```

StochasticPrograms.jl - Simple Example

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    p::Float64
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end
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```
StochasticPrograms.probability(s::SimpleScenario) = s.p
```

Add two scenarios to the stochastic program

```
s1 = SimpleScenario(0.4, [500.0, 100], [-24.0, -28])
```

```
s2 = SimpleScenario(0.6, [300.0, 300], [-28.0, -32])
```

```
append!(sp, [s1, s2])
```



StochasticPrograms.jl - Simple Example

```
print(sp)
```

StochasticPrograms.jl - Simple Example

```
print(sp)
```

First-stage

```
=====
Min 100 x1 + 150 x2
Subject to
x1 + x2 ≤ 120
x1 ≥ 40
x2 ≥ 20
```

Second-stage

```
=====
Subproblem 1:
Min -24 y1 - 28 y2
Subject to
6 y1 + 10 y2 - 60 x1 ≤ 0
8 y1 + 5 y2 - 80 x2 ≤ 0
0 ≤ y1 ≤ 500
0 ≤ y2 ≤ 100
```

Subproblem 2:

```
Min -28 y1 - 32 y2
Subject to
6 y1 + 10 y2 - 60 x1 ≤ 0
8 y1 + 5 y2 - 80 x2 ≤ 0
0 ≤ y1 ≤ 300
0 ≤ y2 ≤ 300
```

Implementation Details

Deferred model creation

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- Flexible model creation and reformulation
- Efficient parallel implementation

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Implications

- Flexible model creation and reformulation
- Efficient parallel implementation
- Versatility

StochasticPrograms.jl - Deterministically Equivalent Model

$$\begin{aligned} \underset{x \in \mathbb{R}^n}{\text{minimize}} \quad & c^T x + \mathbb{E}_\omega[Q(x, \xi(\omega))] \\ \text{s.t.} \quad & Ax = b \end{aligned}$$

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dep = DEP(sp)

Minimization problem with:

* 5 linear constraints

* 6 variables

Solver is ClpMathProg

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- Second stage generator on all available scenarios

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dep = DEP(sp)

Minimization problem with:

* 5 linear constraints

* 6 variables

Solver is ClpMathProg

- First stage generator
- Second stage generator on all available scenarios
- Connections possible due to the `@decision` annotation
- DEP model is cached internally until new scenarios are added



StochasticPrograms.jl - Deterministically Equivalent Model

```
print(dep)
```

StochasticPrograms.jl - Deterministically Equivalent Model

```
print(dep)
```

```
Min 100 x1 + 150 x2 - 9.6 y1_1 - 11.2 y2_1 - 16.8 y1_2 - 19.2 y2_2
```

```
Subject to
```

```
x1 + x2 ≤ 120
```

```
6 y1_1 + 10 y2_1 - 60 x1 ≤ 0
```

```
8 y1_1 + 5 y2_1 - 80 x2 ≤ 0
```

```
6 y1_2 + 10 y2_2 - 60 x1 ≤ 0
```

```
8 y1_2 + 5 y2_2 - 80 x2 ≤ 0
```

```
x1 ≥ 40
```

```
x2 ≥ 20
```

```
0 ≤ y1_1 ≤ 500
```

```
0 ≤ y2_1 ≤ 100
```

```
0 ≤ y1_2 ≤ 300
```

```
0 ≤ y2_2 ≤ 300
```



StochasticPrograms.jl - Solving Models

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- Extended form

```
solve(sp,solver=ClpSolver())  
:Optimal
```

```
getobjectivevalue(sp)  
-855.83
```

StochasticPrograms.jl - Solving Models

- Extended form

```
solve(sp,solver=ClpSolver())  
:Optimal
```

```
getobjectivevalue(sp)  
-855.83
```

- L-shaped

```
solve(sp,solver=LShapedSolver(:ls,ClpSolver()))
```

```
L-Shaped Gap Time: 0:00:01 (4 iterations)  
Objective:      -855.83333333333358  
Gap:            2.1229209144670507e-15  
Number of cuts: 5  
:Optimal
```

StochasticPrograms.jl - Solving Models

- Extended form

```
solve(sp,solver=ClpSolver())  
:Optimal
```

```
getobjectivevalue(sp)  
-855.83
```

- L-shaped

```
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```

```
L-Shaped Gap Time: 0:00:01 (4 iterations)  
Objective:      -855.83333333333358  
Gap:           2.1229209144670507e-15  
Number of cuts: 5  
:Optimal
```

- Convenience function (Value of the recourse problem)

```
VRP(sp,solver=ClpSolver())  
-855.83
```

StochasticPrograms.jl - Wait-And-See Models

$$\begin{aligned} & \underset{x \in \mathbb{R}^n}{\text{minimize}} && c^T x + Q(x, \tilde{\xi}) \\ & \text{s.t.} && Ax = b \\ & && x \geq 0 \end{aligned}$$

for given $\tilde{\xi}$

StochasticPrograms.jl - Wait-And-See Models

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for given $\tilde{\xi}$

```
ws = WS(sp,s1)
```

```
Minimization problem with:
```

- * 3 linear constraints
- * 4 variables

```
Solver is ClpMathProg
```

StochasticPrograms.jl - Wait-And-See Models

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for given $\tilde{\xi}$

`ws = WS(sp,s1)`

Minimization problem with:

- * 3 linear constraints
- * 4 variables

Solver is ClpMathProg

- First stage generator

StochasticPrograms.jl - Wait-And-See Models

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for given $\tilde{\xi}$

`ws = WS(sp,s1)`

Minimization problem with:

- * 3 linear constraints
- * 4 variables

Solver is ClpMathProg

- First stage generator
- Second stage generator on the given scenario



StochasticPrograms.jl - Wait-And-See Models

```
print(ws)
```

StochasticPrograms.jl - Wait-And-See Models

```
print(ws)
```

```
Min 100 x1 + 150 x2 - 24 y1 - 28 y2
```

```
Subject to
```

$$x_1 + x_2 \leq 120$$

$$6 y_1 + 10 y_2 - 60 x_1 \leq 0$$

$$8 y_1 + 5 y_2 - 80 x_2 \leq 0$$

$$x_1 \geq 40$$

$$x_2 \geq 20$$

$$0 \leq y_1 \leq 500$$

$$0 \leq y_2 \leq 100$$

StochasticPrograms.jl - Expected Value Problems

$$\begin{aligned} & \underset{x \in \mathbb{R}^n}{\text{minimize}} && c^T x + Q(x, \bar{\xi}) \\ & \text{s.t.} && Ax = b \\ & && x \geq 0 \end{aligned}$$

where

$$\bar{\xi} = \mathbb{E}_\omega[\xi(\omega)]$$

StochasticPrograms.jl - Expected Value Problems

$$\begin{aligned} & \underset{x \in \mathbb{R}^n}{\text{minimize}} && c^T x + Q(x, \bar{\xi}) \\ & \text{s.t.} && Ax = b \\ & && x \geq 0 \end{aligned}$$

where

$$\bar{\xi} = \mathbb{E}_{\omega}[\xi(\omega)]$$

Must be possible to take expectation over scenarios

```
function expected(scenarios::Vector{SimpleScenario})  
    return SimpleScenario(sum([s.p for s in scenarios]),  
                           sum([s.p*s.d for s in scenarios]),  
                           sum([s.p*s.q for s in scenarios]))  
end
```

StochasticPrograms.jl - Expected Value Problems

```
evp = EVP(sp)
Minimization problem with:
 * 3 linear constraints
 * 4 variables
Solver is ClpMathProg

print(evp)
```

StochasticPrograms.jl - Expected Value Problems

```
evp = EVP(sp)
```

```
Minimization problem with:
```

```
* 3 linear constraints
```

```
* 4 variables
```

```
Solver is ClpMathProg
```

```
print(evp)
```

```
Min 100 x1 + 150 x2 - 26.4 y1 - 30.4 y2
```

```
Subject to
```

```
x1 + x2 ≤ 120
```

```
6 y1 + 10 y2 - 60 x1 ≤ 0
```

```
8 y1 + 5 y2 - 80 x2 ≤ 0
```

```
x1 ≥ 40
```

```
x2 ≥ 20
```

```
0 ≤ y1 ≤ 380
```

```
0 ≤ y2 ≤ 220
```

$$c^T \hat{x} + \mathbb{E}_\omega[Q(\hat{x}, \xi(\omega))]$$

StochasticPrograms.jl - Decision Evaluation

$$c^T \hat{x} + \mathbb{E}_\omega[Q(\hat{x}, \xi(\omega))]$$

```
 $\hat{x}$  = [50,50];
```

```
eval_decision(sp,  $\hat{x}$  , solver=ClpSolver())  
356.0
```

- Create first stage variables using generator

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- Solve resulting JuMP model

StochasticPrograms.jl - Stochastic Measures

- Expected value of using the expected solution (EEV)

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EEV(sp,solver=ClpSolver())  
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```

- Value of the stochastic solution (VSS = EEV - VRP)

```
VSS(sp,solver=ClpSolver())  
286.92
```

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Many of the required calculations are embarassingly parallel

L-shaped algorithm variants

- L-shaped [Van Slyke,Wets]
- Multicut L-shaped [Birge,Louveaux]
- Regularized decomposition [Ruszczynski]
- Trust-region L-shaped [Linderth,Wright]
- Level-set [Fábián,Szöke]

- **L-shaped variants**

1. L-shaped with multiple cuts (default): `LShapedSolver(:ls)`
2. L-shaped with regularized decomposition: `LShapedSolver(:rd)`
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- **Distributed L-shaped variants**

1. Distributed L-shaped with multiple cuts: `LShapedSolver(:dls)`
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- Subproblems are solved using MathProgBase solvers

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Creating a Planning Problem

- Define model indices
- Define model data
- Define `modelindices(::AbstractHydroModelData, ::Horizon, args...)`
- Define optimization problem

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Data injection keywords

- *horizon*: the time horizon if the model
- *indices*: structure with model indices
- *data*: structure with model data

HydroModels.jl - Simple Example

```
struct SimpleShortTermIndices <: AbstractModelIndices
    hours::Vector{Int}
    plants::Vector{Symbol}
end
```

```
struct SimpleShortTermData <: AbstractModelData
    hydrodata::HydroPlantCollection{Float64,2}
    D::Vector{Float64} # Load balance
    λ::Vector{Float64} # Price curve
end
```

```
function modelindices(data::SimpleShortTermData, horizon::Horizon)
    hours = collect(1:nhours(horizon))
    plants = data.hydrodata.plants
    if isempty(plants)
        error("No plants in data")
    end
    return SimpleShortTermIndices(hours, plants)
end
```

Define the required model indices

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Define data structure that should be available in the model

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    end
    return SimpleShortTermIndices(hours, plants)
end
```

Create model indices based on given data and time horizon

HydroModels.jl - Simple Example

```
@hydromodel Deterministic SimpleShortTerm = begin
    ...
    hours = indices.hours
    plants = indices.plants
    ...
    hdata = data.hydrodata
    D = data.D
    λ = data.λ
    ...
    @variable(model, H[t = hours] >= 0) # Production each hour
    ...
    @expression(model, value_of_stored_water,
        0.98*mean(λ)*sum(M[p,24]*sum(hdata[i].μ[1]
            for i = hdata.Qd[p])
            for p = plants))
    @objective(model, Max, net_profit + value_of_stored_water)
    ...
    @constraint(model, load_constraint[t = hours],
        H[t] + Hp[t] - Hs[t] == D[t])
    ...
end
```

HydroModels.jl - Simple Example

```
simple_model = SimpleShortTermModel(Day(),data)
```

Deterministic Hydro Power Model : Simple Short Term
including 5 power stations
over a 24 hour horizon (1 day)

Not yet planned

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plan!(simple_model, optimsolver = CbcSolver())
```

Deterministic Hydro Power Model : Simple Short Term
including 5 power stations
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Optimally planned

HydroModels.jl - Simple Example

```
reinitialize!(simple_model,Week(),data)
```

Deterministic Hydro Power Model : Simple Short Term
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- HydroModels.jl model implemented using StochasticPrograms.jl
- Determine optimal order strategies on day-ahead electricity markets
- Small benchmark
 - 257 Swedish power stations
 - 20 Price curve scenarios from the NordPool market
 - 748042 variables and 376700 constraints in the extended form
- Results
 - Gurobi on extended form: 58.2 seconds (+ 9.2s for DEP generation)
 - Distributed L-shaped: 31.5 seconds
 - Distributed L-shaped with tuned trust-region: 26.7 seconds

Final Remarks - Outlook on Future Work

- StochasticPrograms.jl
 - Sampling
 - Multistage models
 - Progressive hedging solver

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 - Implement more models of hydropower operations
- LShapedSolvers.jl
 - Algorithmic improvements
 - Hardware acceleration
 - Support integer problems

Final Remarks - Summary

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 - StochasticPrograms.jl
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 - StochasticPrograms.jl
 - LShapedSolvers.jl
 - HydroModels.jl
- Software innovations
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- Disclaimer: Not updated for MathOptInterface and JuMP 0.19
- All packages are available on Github:
 - <https://github.com/martinbiel/StochasticPrograms.jl>
 - <https://github.com/martinbiel/LShapedSolvers.jl>
 - <https://github.com/martinbiel/HydroModels.jl>

Feedback appreciated!